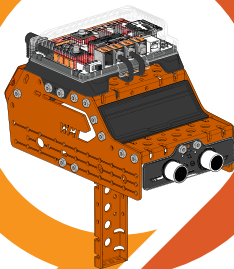


Distance Measuring Robot

WEEEBot Extended Form B



Maker



Coding

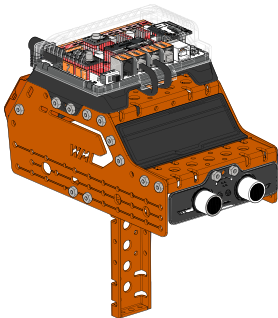


Robot



Introduction

Distance measuring robot is using ultrasonic sensor and mechanical parts to build a hand-held distance measuring machine.

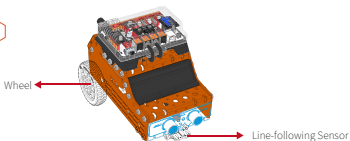


1 Disassembly

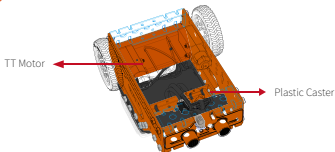
Distance measuring robot is transformed from WeeeBot coding robot car. Please disassemble below parts from WeeeBot coding robot car, and then follow assembly guide to build distance measuring robot.

Tips: Please disassemble parts marked in Black line and put them back into box; please disassemble parts marked in Blue line and keep them to build distance measuring robot.

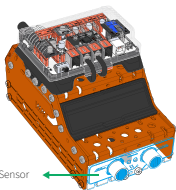
1



2



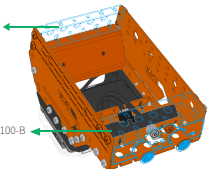
3



RGB Ultrasonic Sensor

4

Beam 1030-100-B



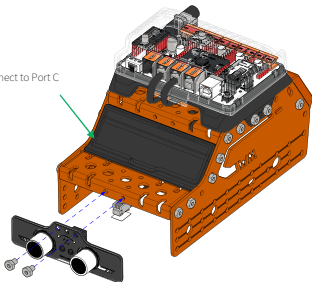
Beam 1030-100-B



2

Install RGB Ultrasonic Sensor

Connect to Port C

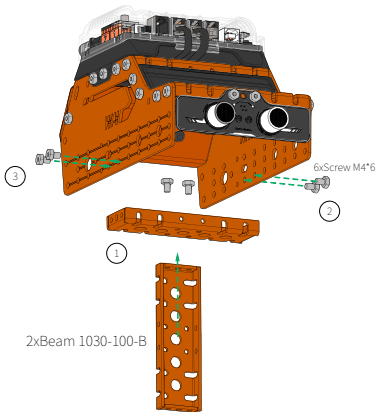


2xScrew M4*6

Connect to Port B

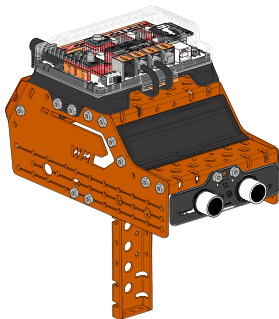


3 Install Handle





4 Completion Figure



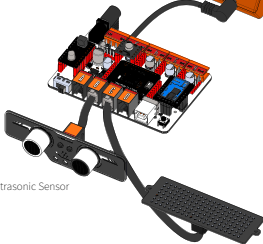


5 Wiring

18650 Battery Holder



RGB Ultrasonic Sensor



LED Panel Module





6 Sample Program

Display ultrasonic detecting value on the LED matrix panel

when program begin

forever

led matrix PortC ▼ show number ultrasonic PortB ▼

ultrasonic PortB ▼ led Both ▼ R 255 G 255 B 255

wait 1 secs

ultrasonic PortB ▼ led Both ▼ R 0 G 0 B 0

wait 1 secs

Turn on the RGB

Turn off the RGB



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